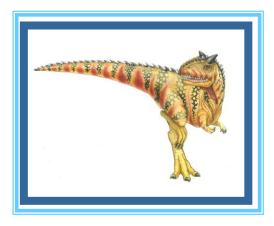
Chapter 1: Introduction



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What is an Operating System?

- A program that acts as an intermediary between a user of a computer and the computer hardware
- Operating system goals:
 - Execute user programs and make solving user problems easier
 - Make the computer system convenient to use
 - Use the computer hardware in an efficient manner





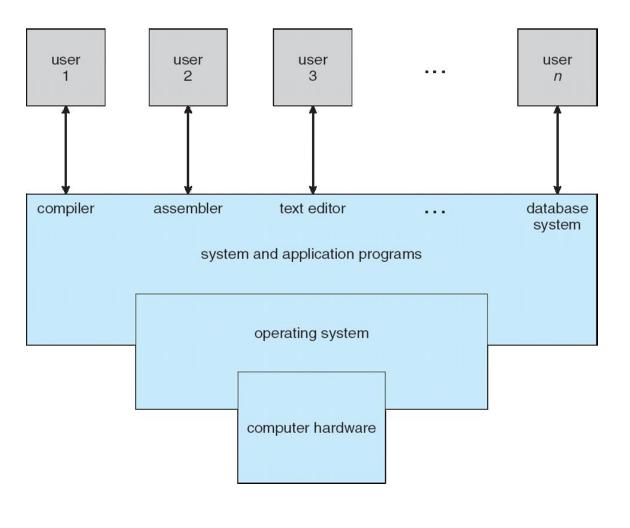
Computer System Structure

Computer system can be divided into four components

- Hardware provides basic computing resources
 - CPU, memory, I/O devices
- Operating system
 - Controls and coordinates use of hardware among various applications and users
- Application programs define the ways in which the system resources are used to solve the computing problems of the users
 - Word processors, compilers, web browsers, database systems, video games
- Users
 - People, machines, other computers



Four Components of a Computer System





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Operating System Concepts



Operating System Definition

- OS is a resource allocator
 - Manages all resources
 - Decides between conflicting requests for efficient and fair resource use
- OS is a control program
 - Controls execution of programs to prevent errors and improper use of the computer





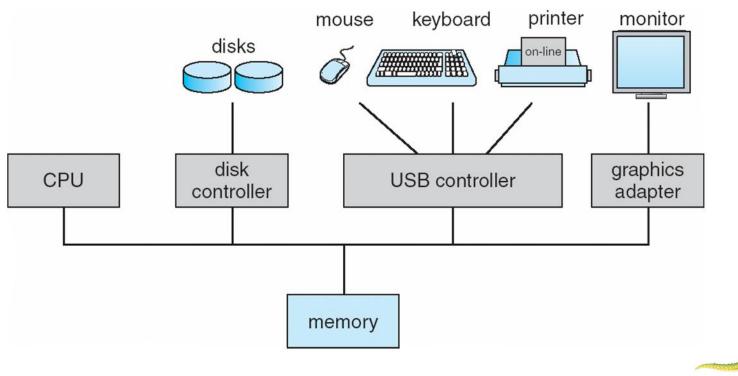
bootstrap program is loaded at power-up or reboot

- Typically stored in ROM or EPROM, generally known as firmware
- Initializes all aspects of system
- Loads operating system kernel and starts execution
- "The one program running at all times on the computer" is the kernel. Everything else is either a system program (ships with the operating system) or an application program





- Computer-system operation
 - One or more CPUs, device controllers connect through common bus providing access to shared memory
 - Concurrent execution of CPUs and devices competing for memory cycles





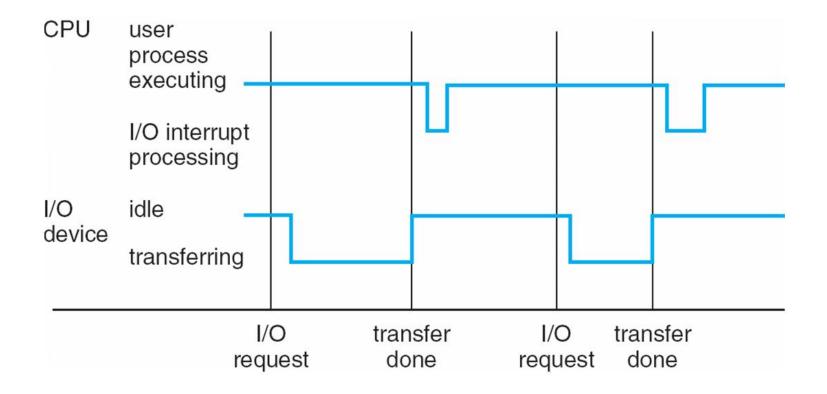
Computer-System Operation

- I/O devices and the CPU can execute concurrently
- Each device controller is in charge of a particular device type
- Device controller informs CPU that it has finished its operation by causing an *interrupt*
- An operating system is interrupt driven





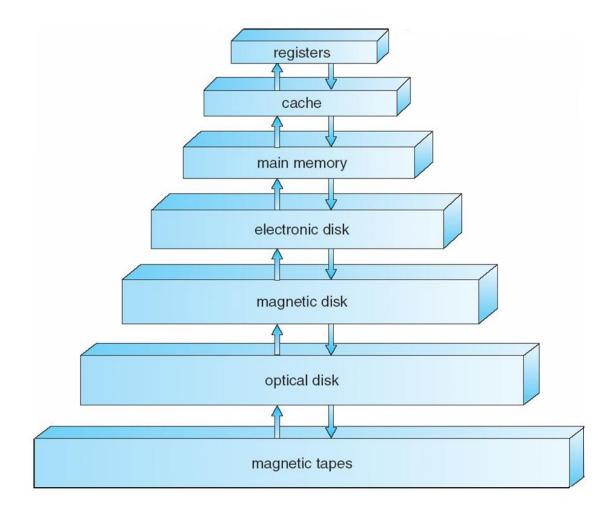
Interrupt Timeline







Storage-Device Hierarchy





Operating System Concepts

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Caching

- Important principle, performed at many levels in a computer (in hardware, operating system, software)
- Information in use copied from slower to faster storage temporarily
- Faster storage (cache) checked first to determine if information is there
 - If it is, information used directly from the cache (fast)
 - If not, data copied to cache and used there
- Cache smaller than storage being cached
 - Cache management important design problem
 - Cache size and replacement policy



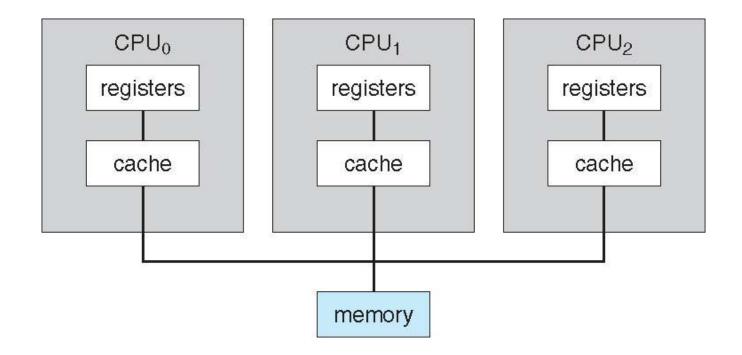
Computer-System Architecture

Multiprocessors systems growing in use and importance

- Also known as parallel systems, tightly-coupled systems
- Advantages include
 - 1. Increased throughput
 - 2. Economy of scale
 - 3. Increased reliability graceful degradation or fault tolerance
- Two types
 - 1. Asymmetric Multiprocessing
 - 2. Symmetric Multiprocessing



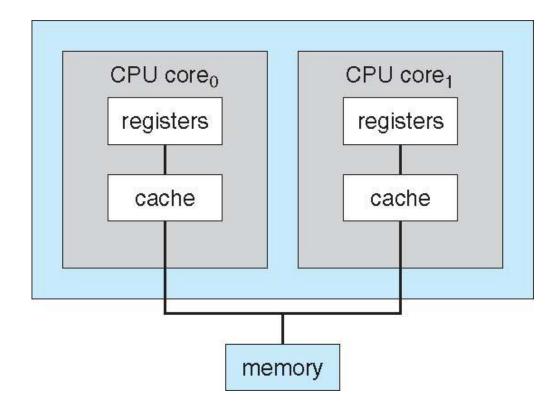








A Dual-Core Design





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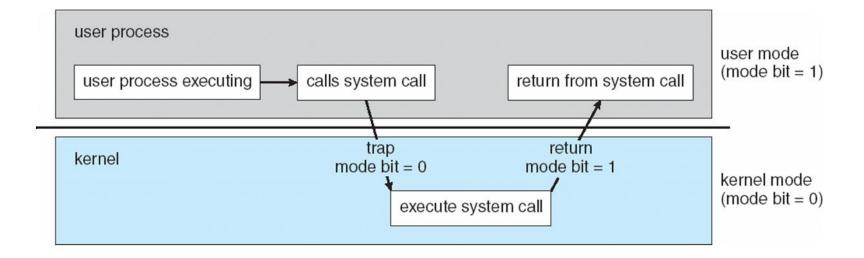


Operating-System Operations

- Interrupt driven by hardware
- Software error or request creates exception or trap
 - Division by zero, request for operating system service
- Dual-mode operation allows OS to protect itself and other system components
 - User mode and kernel mode
 - Mode bit provided by hardware
 - Provides ability to distinguish when system is running user code or kernel code
 - Some instructions designated as privileged, only executable in kernel mode
 - > System call changes mode to kernel, return from call resets it to user



Transition from User to Kernel Mode





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Operating System Concepts



- A process is a program in execution. It is a unit of work within the system. Program is a passive entity, process is an active entity.
- Process needs resources to accomplish its task
 - CPU, memory, I/O, files
 - Initialization data
- Process termination requires reclaim of any reusable resources
- Single-threaded process has one program counter specifying location of next instruction to execute
 - Process executes instructions sequentially, one at a time, until completion
- Multi-threaded process has one program counter per thread
- Typically system has many processes, some user, some operating system running concurrently on one or more CPUs
 - Concurrency by multiplexing the CPUs among the processes / threads



Process Management Activities

The operating system is responsible for the following activities in connection with process management:

- Creating and deleting both user and system processes
- Suspending and resuming processes
- Providing mechanisms for process synchronization
- Providing mechanisms for process communication
- Providing mechanisms for deadlock handling





- All data in memory before and after processing
- All instructions in memory in order to execute
- Memory management determines what is in memory when
 - Optimizing CPU utilization and computer response to users
- Memory management activities
 - Keeping track of which parts of memory are currently being used and by whom
 - Deciding which processes (or parts thereof) and data to move into and out of memory
 - Allocating and deallocating memory space as needed





- OS provides uniform, logical view of information storage
 - Abstracts physical properties to logical storage unit file
 - Each medium is controlled by device (i.e., disk drive, tape drive)
 - Varying properties include access speed, capacity, datatransfer rate, access method (sequential or random)
- File-System management
 - Files usually organized into directories
 - Access control on most systems to determine who can access what
 - OS activities include
 - Creating and deleting files and directories
 - Primitives to manipulate files and dirs
 - Mapping files onto secondary storage
 - Backup files onto stable (non-volatile) storage media





Movement between levels of storage hierarchy can be explicit or implicit

Level	1	2	3	4	
Name	registers	cache	main memory	disk storage	
Typical size	< 1 KB	> 16 MB	> 16 GB	> 100 GB	
Implementation technology	custom memory with multiple ports, CMOS	on-chip or off-chip CMOS SRAM	CMOS DRAM	magnetic disk	
Access time (ns)	0.25 - 0.5	0.5 – 25	80 - 250	5,000.000	
Bandwidth (MB/sec)	20,000 - 100,000	5000 - 10,000	1000 - 5000	20 – 150	
Managed by	compiler	hardware	operating system	operating system	
Backed by	cache	main memory	disk	CD or tape	

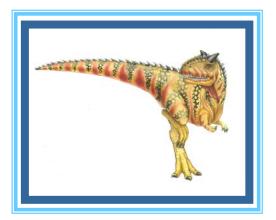


Open-Source Operating Systems

- Operating systems made available in source-code format rather than just binary closed-source
- Counter to the copy protection and Digital Rights Management (DRM) movement
- Started by Free Software Foundation (FSF), which has "copyleft" GNU Public License (GPL)
- Examples include GNU/Linux, BSD UNIX (including core of Mac OS X), and Sun Solaris



Chapter 2: Operating-System Structures



Chapter 2: Operating-System Structures

- Operating System Services
- User Operating System Interface
- System Calls
- Types of System Calls
- System Programs
- Operating System Design and Implementation
- Operating System Structure
- Operating System Debugging
- Operating System Generation
- System Boot



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Operating System Services

- Operating systems provide an environment for execution of programs and services to programs and users
- One set of operating-system services provides functions that are helpful to the user:
 - User interface Almost all operating systems have a user interface (UI).
 - Varies between Command-Line (CLI), Graphics User Interface (GUI), Batch
 - Program execution The system must be able to load a program into memory and to run that program, end execution, either normally or abnormally (indicating error)
 - I/O operations A running program may require I/O, which may involve a file or an I/O device



Operating System Services (Cont.)

- One set of operating-system services provides functions that are helpful to the user (Cont.):
 - File-system manipulation The file system is of particular interest. Programs need to read and write files and directories, create and delete them, search them, list file Information, permission management.
 - Communications Processes may exchange information, on the same computer or between computers over a network
 - Communications may be via shared memory or through message passing (packets moved by the OS)
 - **Error detection** OS needs to be constantly aware of possible errors
 - May occur in the CPU and memory hardware, in I/O devices, in user program
 - For each type of error, OS should take the appropriate action to ensure correct and consistent computing
 - Debugging facilities can greatly enhance the user's and programmer's abilities to efficiently use the system

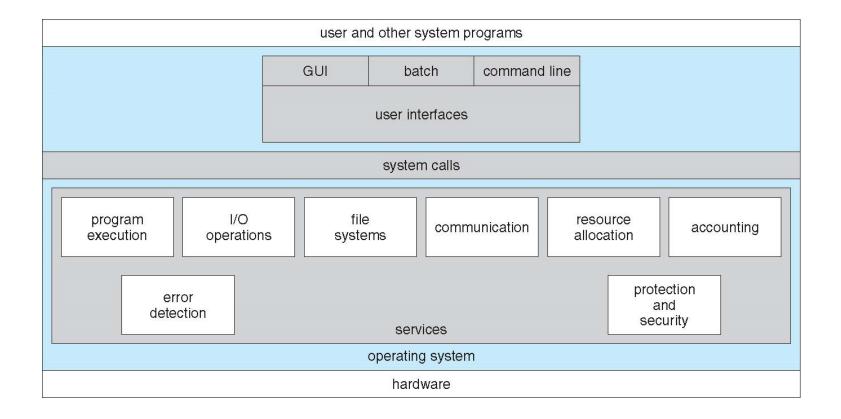


Operating System Services (Cont.)

- Another set of OS functions exists for ensuring the efficient operation of the system itself via resource sharing
 - Resource allocation When multiple users or multiple jobs running concurrently, resources must be allocated to each of them
 - Many types of resources CPU cycles, main memory, file storage, I/O devices.
 - Accounting To keep track of which users use how much and what kinds of computer resources
 - Protection and security The owners of information stored in a multiuser or networked computer system may want to control use of that information, concurrent processes should not interfere with each other
 - Protection involves ensuring that all access to system resources is controlled
 - Security of the system from outsiders requires user authentication, extends to defending external I/O devices from invalid access attempts









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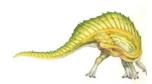
CLI or command interpreter allows direct command entry

- Sometimes implemented in kernel, sometimes by systems program
- Sometimes multiple flavors implemented shells
- Primarily fetches a command from user and executes it
- Sometimes commands built-in, sometimes just names of programs
 - If the latter, adding new features doesn't require shell modification





- User-friendly desktop metaphor interface
 - Usually mouse, keyboard, and monitor
 - Icons represent files, programs, actions, etc
 - Various mouse buttons over objects in the interface cause various actions (provide information, options, execute function, open directory (known as a folder)
 - Invented at Xerox PARC
- Many systems now include both CLI and GUI interfaces
 - Microsoft Windows is GUI with CLI "command" shell
 - Apple Mac OS X is "Aqua" GUI interface with UNIX kernel underneath and shells available
 - Unix and Linux have CLI with optional GUI interfaces (CDE, KDE, GNOME)





Touchscreen Interfaces

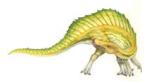
- n Touchscreen devices require new interfaces
 - Mouse not possible or not desired
 - Actions and selection based on gestures
 - Virtual keyboard for text entry
 - Voice commands.





System Calls

- Programming interface to the services provided by the OS
- □ Typically written in a high-level language (C or C++)
- Mostly accessed by programs via a high-level Application Programming Interface (API) rather than direct system call use
- Three most common APIs are Windows API for Windows, POSIX API for POSIX-based systems (including virtually all versions of UNIX, Linux, and Mac OS X), and Java API for the Java virtual machine (JVM)





Example of System Calls

System call sequence to copy the contents of one file to another file

source file	•	destination file
	Example System Call Sequence Acquire input file name Write prompt to screen Accept input Acquire output file name Write prompt to screen Accept input Open the input file if file doesn't exist, abort Create output file if file exists, abort Loop Read from input file Write to output file Until read fails Close output file Write completion message to screen Terminate normally	



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Example of Standard API

EXAMPLE OF STANDARD API

As an example of a standard API, consider the read() function that is available in UNIX and Linux systems. The API for this function is obtained from the man page by invoking the command

man read

on the command line. A description of this API appears below:

	#include	<unistd.h></unistd.h>					
L	ssize_t	read(int	fd,	void	*buf,	size_t	count)
	return function value name		parameters				

A program that uses the read() function must include the unistd.h header file, as this file defines the ssize_t and size_t data types (among other things). The parameters passed to read() are as follows:

- int fd—the file descriptor to be read
- void *buf —a buffer where the data will be read into
- size_t count—the maximum number of bytes to be read into the buffer

On a successful read, the number of bytes read is returned. A return value of 0 indicates end of file. If an error occurs, read() returns -1.



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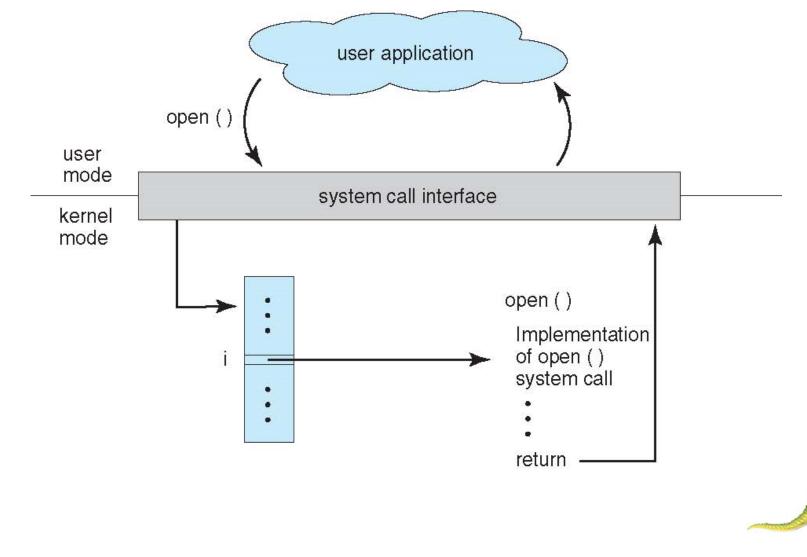
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- □ Typically, a number associated with each system call
 - System-call interface maintains a table indexed according to these numbers
- The system call interface invokes the intended system call in OS kernel and returns status of the system call and any return values
- The caller need know nothing about how the system call is implemented
 - Just needs to obey API and understand what OS will do as a result call
 - Most details of OS interface hidden from programmer by API
 - Managed by run-time support library (set of functions built into libraries included with compiler)









Types of System Calls

- Process control
 - create process, terminate process
 - □ load, execute
 - get process attributes, set process attributes
 - wait for time
 - wait event, signal event
 - □ allocate and free memory
 - Dump memory if error
 - Debugger for determining bugs, single step execution
 - Locks for managing access to shared data between processes





Types of System Calls

- File management
 - □ create file, delete file
 - □ open, close file
 - □ read, write, reposition
 - get and set file attributes
- Device management
 - request device, release device
 - □ read, write, reposition
 - get device attributes, set device attributes
 - logically attach or detach devices





- Information maintenance
 - get time or date, set time or date
 - get system data, set system data
 - get and set process, file, or device attributes
- Communications
 - create, delete communication connection
 - send, receive messages if message passing model to host name or process name
 - From client to server
 - Shared-memory model create and gain access to memory regions
 - □ transfer status information
 - attach and detach remote devices





- Protection
 - Control access to resources
 - Get and set permissions
 - Allow and deny user access



Examples of Windows and Unix System Calls

	Windows	Unix
Process Control	CreateProcess() ExitProcess() WaitForSingleObject()	fork() exit() wait()
File Manipulation	CreateFile() ReadFile() WriteFile() CloseHandle()	open() read() write() close()
Device Manipulation	SetConsoleMode() ReadConsole() WriteConsole()	ioctl() read() write()
Information Maintenance	GetCurrentProcessID() SetTimer() Sleep()	getpid() alarm() sleep()
Communication	CreatePipe() CreateFileMapping() MapViewOfFile()	pipe() shmget() mmap()
Protection	SetFileSecurity() InitlializeSecurityDescriptor() SetSecurityDescriptorGroup()	chmod() umask() chown()

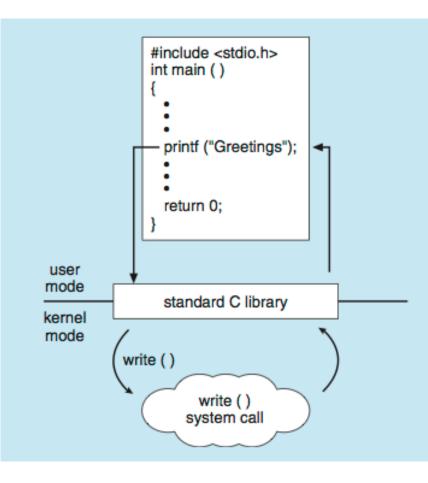


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□ C program invoking printf() library call, which calls write() system call





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- Design and Implementation of OS not "solvable", but some approaches have proven successful
- □ Internal structure of different Operating Systems can vary widely
- Start the design by defining goals and specifications
- □ Highest level: affected by choice of hardware, type of system
- □ The requirements can be divided into User and System goals
 - User goals operating system should be convenient to use, easy to learn, reliable, safe, and fast
 - System goals operating system should be easy to design, implement, and maintain, as well as flexible, reliable, error-free, and efficient



Operating System Design and Implementation (Cont.)

Important principle to separate

Policy: *What* will be done? **Mechanism:** *How* to do it?

- Mechanisms determine how to do something, policies decide what will be done
- The separation of policy from mechanism is a very important principle, it allows maximum flexibility if policy decisions are to be changed later (example – timer)
- Specifying and designing an OS is highly creative task of software engineering





Implementation

- Much variation
 - Early OSes in assembly language
 - □ Then system programming languages like Algol, PL/1
 - Now C, C++
- Actually usually a mix of languages
 - E Lowest levels in assembly
 - Main body in C
 - Systems programs in C, C++, scripting languages like PERL, Python, shell scripts
- More high-level language easier to **port** to other hardware
 - But slower
- **Emulation** can allow an OS to run on non-native hardware





Operating System Structure

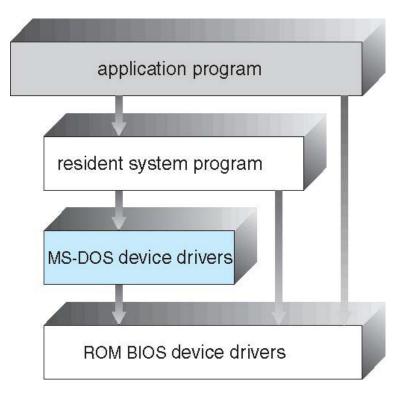
- □ General-purpose OS is very large program
- Various ways to structure ones
 - □ Simple structure MS-DOS
 - More complex -- UNIX
 - Layered an abstrcation
 - Microkernel -Mach

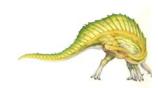


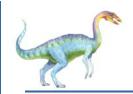


Simple Structure -- MS-DOS

- MS-DOS written to provide the most functionality in the least space
 - Not divided into modules
 - Although MS-DOS has some structure, its interfaces and levels of functionality are not well separated







UNIX – limited by hardware functionality, the original UNIX operating system had limited structuring. The UNIX OS consists of two separable parts

- Systems programs
- The kernel
 - Consists of everything below the system-call interface and above the physical hardware
 - Provides the file system, CPU scheduling, memory management, and other operating-system functions; a large number of functions for one level



Traditional UNIX System Structure

Beyond simple but not fully layered

		(the users)	
	shells and commands compilers and interpreters system libraries		
ſ	system-call interface to the kernel		
Kernel	signals terminal handling character I/O system terminal drivers	file system swapping block I/O system disk and tape drivers	CPU scheduling page replacement demand paging virtual memory
l	kernel interface to the hardware		
-	terminal controllers terminals	device controllers disks and tapes	memory controllers physical memory

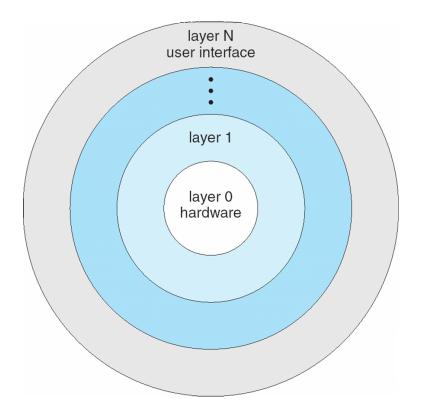


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Layered Approach

- The operating system is divided into a number of layers (levels), each built on top of lower layers. The bottom layer (layer 0), is the hardware; the highest (layer N) is the user interface.
- With modularity, layers are selected such that each uses functions (operations) and services of only lower-level layers
- Simplifies debugging and system verification





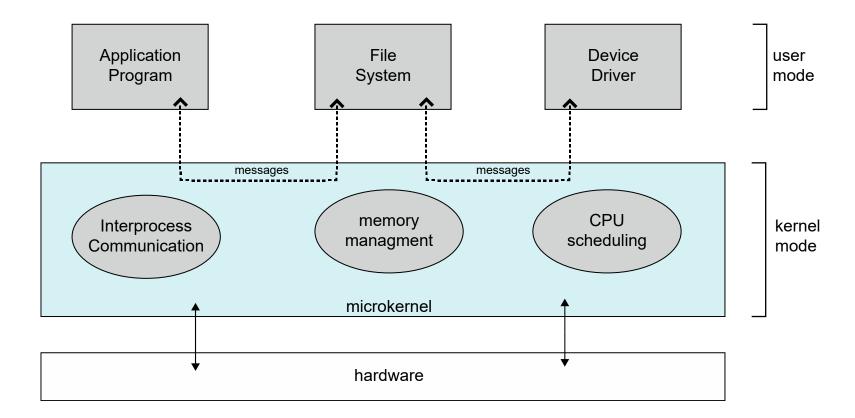


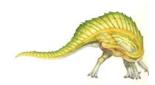
Microkernel System Structure

- Moves as much from the kernel into user space
- Mach example of microkernel
 - Mac OS X kernel (Darwin) partly based on Mach
- Communication takes place between user modules using message passing
- Benefits:
 - Easier to extend a microkernel
 - Easier to port the operating system to new architectures
 - More reliable (less code is running in kernel mode)
 - More secure
- Detriments:
 - Performance overhead of user space to kernel space communication









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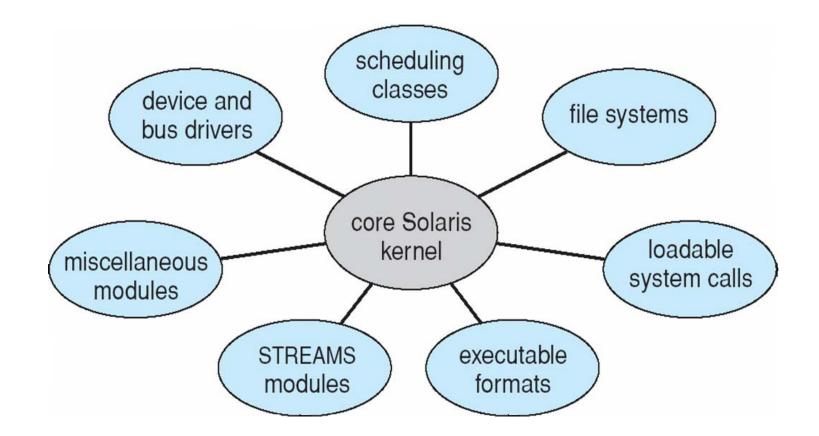
Modules

- Many modern operating systems implement loadable kernel modules
 - Uses object-oriented approach
 - Each core component is separate
 - Each talks to the others over known interfaces
 - Each is loadable as needed within the kernel
- Overall, similar to layers but with more flexible
 - Linux, Solaris, etc





Solaris Modular Approach





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Hybrid Systems

- Most modern operating systems are actually not one pure model
 - Hybrid combines multiple approaches to address performance, security, usability needs
 - Linux and Solaris kernels in kernel address space, so monolithic, plus modular for dynamic loading of functionality
 - Windows mostly monolithic, plus microkernel for different subsystem





Operating System Generation

- Operating systems are designed to run on any of a class of machines; the system must be configured for each specific computer site
- n SYSGEN program obtains information concerning the specific configuration of the hardware system
 - Used to build system-specific compiled kernel or systemtuned
 - Can general more efficient code than one general kernel





System Boot

- When power initialized on system, execution starts at a fixed memory location
 - □ Firmware ROM used to hold initial boot code
- Operating system must be made available to hardware so hardware can start it
 - Small piece of code bootstrap loader, stored in ROM or EEPROM locates the kernel, loads it into memory, and starts it
 - Sometimes two-step process where boot block at fixed location loaded by ROM code, which loads bootstrap loader from disk
- Common bootstrap loader, GRUB, allows selection of kernel from multiple disks, versions, kernel options
- Kernel loads and system is then running

